

This is an explanation of:

multivariate probability distributions

marginal probability distributions

conditional probability

Bayes' theorem

events

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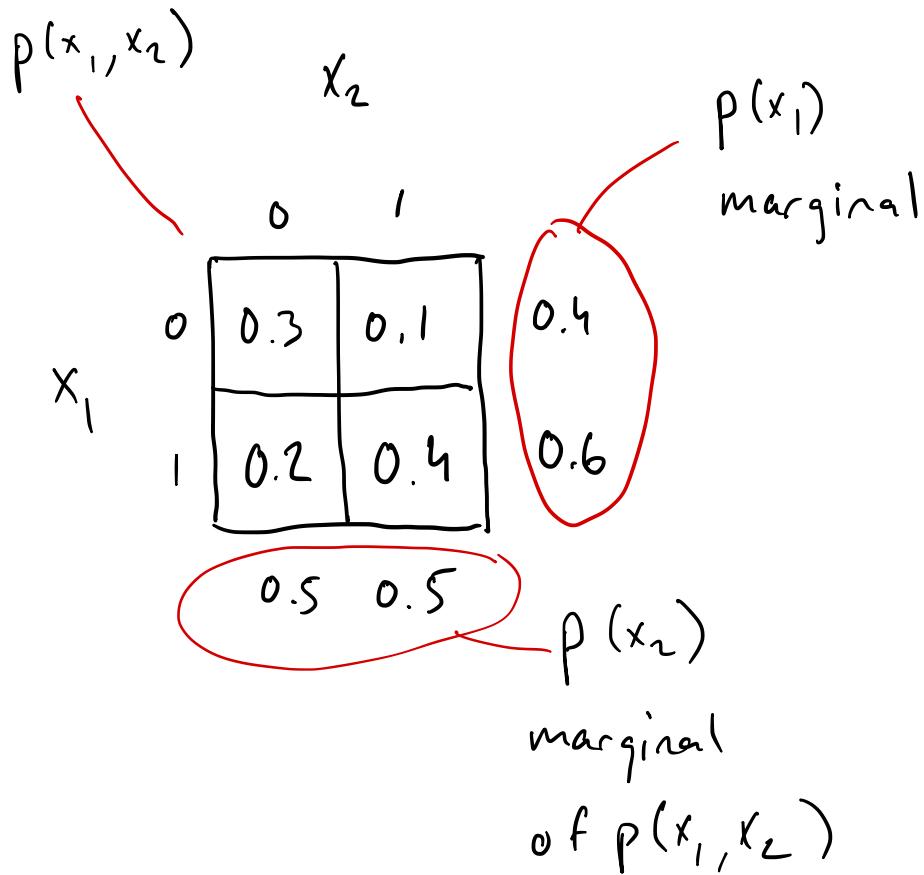
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Now, what happens if we know  $x_1=0$ ?

How update with this new information?

filtered events:

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$$p(x_1, x_2 | x_1=0)$$

		$x_2$		$p(x_1   x_1=0)$
		0	1	
$x_1$	0	0.75	0.25	1
	1	0	0	0
		0.75	0.25	

from original table!

$$p(x_2 | x_1=0) = \frac{p(x_1=0, x_2)}{p(x_1=0)}$$

Same if  $x_1 = 1$

$$p(x_2 | x_1 = 1) = \frac{p(x_1 = 1, x_2)}{p(x_1 = 1)}$$

0	0
0.33	0.67
0.33	0.67

So generally

$$p(x_2 | x_1) = \frac{p(x_1, x_2)}{p(x_1)}$$

and similarly

$$p(x_1 | x_2) = \frac{p(x_1, x_2)}{p(x_2)}$$

0.75	0.25
0.33	0.67

$\Rightarrow$

marginal multiplied back to  
 $p(x_2|x_1)$  to get the original  $p(x_1, x_2)$ !

$$p(x_1)p(x_2|x_1) = p(x_1, x_2) = p(x_2)p(x_1, x_2)$$



Bayes theorem!

this part often  
left out!

Think in whole tables and  
not just in single numbers!

$$p(x_1, x_2, x_3, x_4)$$

we can then just multiply  
the marginals!

if independent

$$p(x_1, x_2, x_3, x_4) = p(x_1) p(x_2) p(x_3) p(x_4)$$

if pairwise dependent in chain (Markov)

$$p(x_1, x_2, x_3, x_4) = p(x_1) p(x_2|x_1) p(x_3|x_2) p(x_4|x_3)$$

(follows from repeated application of Bayes theorem and the Markov property)